

Tutorials

- Editor: Dr. Braham Himed, Air Force Research Lab, Sensors Directorate
- Three papers reviewed and corrections are being made
 - Basic Tracking using 3D Monostatic and Bistatic Measurements
 - Maximum Likelihood Estimation of Target Direction in a Digital Beamforming (DBF) Radar System
 - Basic Tracking Using 3D Monostatic and Bistatic Measurements in Refractive Environments
- Invited four authors/papers Awaiting submission into IEEE process
 - Synthetic Aperture Radar (SAR) Interferometry
 - Cognitive RF (jamming, radio, and radar) Sensing
 - Automatic Target Recognition and Classification
 - Over the Horizon Radar
- Predominance of radar detection and tracking papers
- Expanding to other topics Power, sensor networks, position, navigation, and timing
- Actively soliciting additional authors/papers