IEEE TRANSACTIONS ON
AEROSPACE AND ELECTRONIC SYSTEMS

FEBRUARY 2025 VOLUME 61 NUMBER 1 IEARAX (ISSN 0018-9251)

PAPERS

Power Allocation for Cooperative Localization in Decentralized Distributed Radar Networks: A Nash Bargaining Game Approach ..... *B. Jin, S. Liu, Z. Zhang, Z. Lian, and B. Wang* 4
Frequency Bias Mitigation for Surface User Navigation Using Double Differencing Joint Doppler and Ranging ..... *W. W. Jun, K.-M. Cheung, and E. G. Lightsey* 17
Lidar-Assisted Acquisition of Mobile Airborne FSO Terminals in a GPS-Denied Environment ..... *H. Liu, M. S. Bashir, and M.-S. Alouini* 30
Perception-Aware Based Quadrotor Translation and Yaw Angle Planner in Unpredictable Dynamic Situations ..... *H. Zhang, J. Huo, Y. Huang, and D. Wang* 47
A Parameter Ontology for Simulation Models of Deep Space Habitats ..... *N. Gratius, M. Bergés, and B. Akinci* 61
Robust Controller Design for UAM Using Incremental Nonlinear Dynamic Inversion With Double-Loop Structure ..... *Y. Kim, S. Kim, J. Suk, and H.-S. Shin* 76
Dynamic Event-Triggered Gain-Scheduled H_∞ Control for a Polytopic LPV Model of Morphing Aircraft ..... *G. Cai, T. Wu, M. Hao, H. Liu, and B. Zhou* 93
Modular Multirotary Joints SPS Concept—Challenges and Design Considerations ..... *X. Hou, Z. Cheng, X. Wang, and C. Liu* 107
Phase-Only Beam Forming Method Based on Digital Code Metasurface ..... *S. Yu, D. Guan, Z. Gu, J. Shi, Z. Liu, and Y. Liu* 121
Uninformed Parameter Estimation for Passive Reception of Data Modulated LFM Waveforms ..... *K. Zhang, F. K. Coutts, and J. Thompson* 135
Multistatic-Radar RCS-Signature Recognition of Aerial Vehicles: A Bayesian Fusion Approach ..... *M. Potter, M. Akcakaya, M. Necsoiu, G. Schirner, D. Erdoğmuş, and T. Imbiriba* 151
Reconfigurable Radar Signal Processing Accelerator for Integrated Sensing and Communication System ..... *A. Tewari, S. S. Jha, A. Sneh, S. J. Darak, and S. S. Ram* 162
An Interpretable Data-Driven Learning Approach for Nonlinear Aircraft Systems With Noisy Interference ..... *R. Cao, K. Lu, and Y. Liu* 182
Centrally Synergistic Hybrid Feedback for Global Pose Tracking Using Dual Quaternions ..... *X. Tong and S. S. Cheng* 195
On the Performance of One-Bit Matched Filtering in Massive MIMO Radar ..... *M. Deng, L. Zhou, S. Zhang, Z. Wang, and Z. Cheng* 208
Synergistic Planning for Hypersonic Vehicles With an Analytic Hybrid Algorithm ..... *H. Y. Zhou, X. G. Wang, X. Li, and N. G. Cui* 223
Fisher Information Approach for Masking the Sensing Plan: Applications in Multifunction Radars ..... *S. Jain, V. Krishnamurthy, M. Rangaswamy, B. Kang, and S. Gogineni* 233
Graph-Based Maximum Connected-Component Learning Algorithm for Small Target Detection in Maritime Radars ..... *X. Bai, S. Xu, Z. Guo, and P. Shui* 250
Spinning a Small-Sized Quadrotor Efficiently to Achieve a 3-D Omnidirectional Field of View ..... *S. Yoon, C. Lee, Y. Son, J. J. Son, and S. Han* 266

(Contents Continued on Page 1)

IEEE

(Contents Continued from Front Cover)

Rapid On-Orbit Repair Mission Planning for Multiple GEO Spacecraft Based on a Mixed Repair Strategy . . . . . *H. Yan, L. Yuan, C. Li, Y. Guo, G. Ran, and B. Wang* 279
CoFAR Clutter Estimation Using Covariance-Free Bayesian Learning . . . . . *K. P. Rajput, M. R. B. Shankar, K. V. Mishra, M. Rangaswamy, and B. Ottersten* 296
Disturbance Observer-Based Singularity-Free Predefined-Time Attitude Tracking Control of Quadrotors: Theory and Experiments . . . . . *Z. Zhang, S. Xie, and Q. Chen* 314
Few-Shot Class-Incremental SAR Target Recognition via Orthogonal Distributed Features . . . . . *L. Kong, F. Gao, X. He, J. Wang, J. Sun, H. Zhou, and A. Hussain* 325
3-D Autonomous Entry Trajectory Planning via Hybrid Action Reinforcement Learning . . . . . *G. Peng, B. Wang, L. Liu, and H. Fan* 342
Geometric Feature Extraction of Satellites Based on 3-D Geometry Reconstruction From ISAR Image Sequences . . . . . *Z. Cao, L. Du, Z. Zhuo, J. Chen, and S. Zhu* 355
Two-Step Input Excitation Disturbance Estimation-Based Self-Adjustment Control for Spacecrafts With Multiplicative Uncertainties . . . . . *Y. Zhu, B. Zhu, Y. Cui, and X. Sun* 374
Swarm Characteristics Classification Using Neural Networks . . . . . *D. W. Peltier III, I. Kaminer, A. H. Clark IV, and M. Orescanin* 389
Tangential Maneuvering Target Detection for Airborne Cognitive Radar . . . . . *J. Xiong, G. Cui, T. Fan, Y. Li, X. Yu, L. Kong, and X. Yang* 401
Wideband LPI Radar Subpulse Waveform Design, Processing, and Analysis . . . . . *H. Qiu, X. Yu, G. Cui, J. Yang, and L. Kong* 416
Scaling-Transformation-Based Attitude Tracking Control for Rigid Spacecraft With Prescribed Time and Prescribed Bound . . . . . *Y. Xiao, Y. Yang, D. Ye, and Y. Zhao* 433
Obstacle-Avoidance Distributed Reinforcement Learning Optimal Control for Spacecraft Cluster Flight . . . . . *Y. Meng, C. Liu, J. Zhao, and J. Huang* 443
Proportional Navigation Guidance With Virtual Targeting for Impact Angle Control . . . . . *J. Park, E.-T. Jeong, K.-W. Jung, and C.-H. Lee* 457
RTM-UAVDet: A Real-Time Multimodal UAV Detector . . . *G. Wang, Q. Jiang, X. Jin, M. Wozniak, P. Wang, and S. Yao* 473
Improved Coordinate Registration for Over-the-Horizon Radar: Sampling-Based Approaches . . . . . *Z. Wang, J. Liu, H. Lan, and K. Lu* 490
Likelihood Scouting via Map Inversion for a Posterior-Sampled Particle Filter . . . . . *S. Servadio* 505
Time-Varying Formation-Surrounding Control for Multiquadrotors Pursuit–Evasion Games With Disturbances and Collision Avoidance . . . . . *H. Xiong and Y. Zhang* 522
A Nonstationary Clutter Suppression Algorithm for Space-Based Radar Based on Presequence Pulse Echoes . . . . . *J. Wu, W. Chen, W. Liu, T. Zhang, Z. Zhang, and Y.-L. Wang* 542
Causal CSI-Based Trajectory Design and Power Allocation for UAV-Enabled Wireless Networks Under Average Rate Constraints: A Constrained Reinforcement Learning Approach . . . . . *H. Yu and H.-C. Yang* 554
Solution Space of Minimum-Time Low-Thrust Rephasing in Elliptical Orbit . . . . . *D. Wu, L. Cheng, S. Gong, and H. Baoyin* 568
Dual Lawson Norm-Based Robust DOA Estimation for RIS-Aided Wireless Communication Systems . . . . . *C. Yu, Y. Li, L. Li, Z. Huang, Q. Wu, and R. de Lamare* 582
Radio Frequency Fingerprint Identification Using Conditional Generative Adversarial Network for SAT-AIS . . . . . *Q. Jiang and J. Sha* 593
Aircraft Reinjection on Missed Approach Maneuvers With Progressive Speed Variation . . . . . *M. Carmona, R. Casado, and A. Bermúdez* 603
Prescribed Performance Backstepping Attitude Control of Parafoil System for Rocket Booster Recovery Under Complex Unknown Disturbances . . . . . *X. Xing, L. Qin, Y. Luo, L. Feng, and B. Xiao* 620
Adaptive Attitude Control of Combined Spacecraft With Large Parametric Uncertainties and Adversarial Disturbance . . . . . *X. Guo, Z. Meng, and C. Jia* 632
Improved Lightweight Saliency Model Based on Neural Network for Noncooperative Spacecraft Detection . . . . . *M. Wang, D. Feng, H. Wang, H. Guo, P. Dai, J. Cui, and X. Wang* 642
Adaptive Labeled Multi-Bernoulli Filter With Pairwise Markov Chain Model and Student's *t* Noise . . . . . *Y. Zhou, L. Yan, H. Li, and Y. Xia* 655
Radar Ambiguity Functions of Binary-Coded and Frequency-Hopped Waveforms Designed Based on the Permutations of Sudoku Matrix . . . . . *M. G. M. Hussain and R. M. Narayanan* 669
Asteroid Approach Guidance Based on Predicted Rendezvous Probability . . . . . *S. Zhu, Z. Sui, Y. Jing, Y. Xiu, and D. Ge* 684

(Contents Continued on Page 2)

(Contents Continued from Page 1)

Directional Interference Avoidance With Minimum Interaircraft Interactions for Flying Ad Hoc Networks (FANET) With Directional Antennas Through Distributed Multiagent Reinforcement Learning . . . . . *L. He, J. Zhao, F. Hu, and S. Kumar* 696
Two-Stage Game Guidance Strategy With Impact Point for Active Defense Aircraft in Two-on-Two Engagement . . . . . *X. Wang, M. Yang, S. Wang, and T. Chao* 710
Adaptive Quaternion State Estimation for 3-D and 4-D Signals With Weighted Maximum Correntropy: A Widely Linear Approach . . . . . *D. Lin, S. Wang, Q. Zhang, X. Chen, and C. K. Tse* 730
Acoustic Attack Mitigation Approach for MEMS Inertial Sensors Using Change Point Detection on MhIMU Framework . . . . . *C. Sahu and S. Poddar* 743
AAV 3-D Path Planning Based on MOEA/D With Adaptive Areal Weight Adjustment . . . . . *Y. Xiao, H. Yang, H. Liu, K. Wu, and G. Wu* 753
Similarity to Availability: Synthetic Data Assisted SAR Target Recognition via Global Feature Compensation . . . . . *Z. Cui, H. Hu, Z. Zhou, H. Wang, Z. Cao, and J. Yang* 770
EM-Based Algorithm for Unsupervised Clustering of Measurements from a Radar Sensor Network . . . . . *L. Yan, P. Addabbo, N. Fiscante, C. Clemente, C. Hao, G. Giunta, and D. Orlando* 787
Adaptive Fuzzy Nonsingular Fixed-Time Safety Flight Containment Control for Multi-UAVs . . . . . *H. Wang and M. Li* 802
Event-Triggered Prescribed Performance Adaptive Fuzzy Fault-Tolerant Control for Quadrotor AAV With Actuator Saturation and Failures . . . . . *C. Wang, W. Li, and M. Liang* 813
Principal Gaussian Overbound for Heavy-Tailed Error Bounding . . . . . *P. Yan, Y. Zhong, and L.-T. Hsu* 829
Integrated Target Assignment and Trajectory Optimization for Many-to-Many Midcourse Guidance . . . . . *T. Jin, H.-S. Shin, A. Tsourdos, and S. He* 853
Complexity Evaluation of Aerial Infrared Countermeasure Scenes . . . . . *F. Xie, M. Dong, X. Wang, D. Yang, and J. Yan* 868
Two-Stage Correction for Wavefront Curvature Effects of PFA in Focusing Nonideal Circular SAR Data . . . . . *S. Han, D. Zhu, and X. Mao* 886
Intelligent Decision-Making Approach for Contingency Return Trajectory Based on Production Rule Base and Deep Learning . . . . . *L. Lu, H.-Y. Li, and T.-S. Dong* 900
A Dynamic Event-Triggered Saturation Method for Nonlinear Estimation With Application to Drag-Free Control Systems . . . . . *L. Hao, Y. Zhang, and H. Li* 915
Prescribed-Time Chattering-Free Sliding Mode Guidance Law With Terminal Angle Constraint Based on Periodic Delayed Feedback . . . . . *H. Zheng, B. Zhou, Y. Ding, and M. Hao* 932
A High-Frame-Rate-Imaging-Based Framework for Moving Point Target Detection in Very Low SNR . . . . . *W. Niu, Y. Guo, X. Han, R. Ma, W. Zheng, X. Peng, and Z. Yang* 943
State-of-Charge Estimation for Remaining Flying Time Prediction of Small UAV Using Adaptive Robust Extended Kalman Filter . . . . . *T. Uhm and S. Kim* 959
Optimum Frequency Hop Patterns Constructed on a Golomb Costas Array Using Two-Dimensional Circular Shift . . . . . *J. Yao, R. Jiang, Z. Liu, and X. Wang* 978
Relay-Satellite-Assisted LEO Constellation NOMA Communication System . . . . . *X. Zhang, X. Yue, Z. Han, T. Li, X. Shen, Y. Wang, and R. Liu* 995
Sinusoidal Similarity Among Electromagnetic Reconnaissance Signals and Its Application in Blind Signal Separation . . . . . *L. Pang, Y. Tang, K. Jiang, and W. Zhang* 1012
Secure Cooperative Guidance Strategy for Multimissile System With Collision Avoidance . . . . . *J. Yu, Z. Shi, X. Dong, Q. Li, and Z. Ren* 1034
Collaborative Control of Space Flexible Multiarm Robot Exploiting Stress Stiffening Effect . . . . . *Q. Wei, Y. Song, C. Wei, X. Cao, Y. Qian, and W. Li* 1048
Self-Organizing Multiagent Target Enclosing Under Limited Information and Safety Guarantees . . . . . *P. K. Ranjan, A. Sinha, and Y. Cao* 1066
Robust Velocity Control of a Fixed Canard Decoupled Dual-Spin Projectile . . . . . *S. M. Nayak, J. Singh, M. Kothari, and S. R. Sahoo* 1079
A Coupled Error Self-Calibration Method for High-Speed Space Target Imaging in Stepped-Frequency Radar Based on Minimum Entropy . . . . . *P. Li, L. Li, L. Lv, Z. Dong, Z. Wang, and Z. Ding* 1090
Joint Localization and Source Association Sparse Bayesian Learning Under Multipath Propagation . . . . . *T. Tang, C. Yang, Y. Jiao, D. Chen, and L. Xu* 1104
Improving PA-MIMO Radar Detection Performance Through Transceiver Subarray Configuration Optimization Under QoS-Based Model . . . . . *C. Qi, J. Xie, H. Zhang, C. Zhan, W. Liu, W. Feng, and R. Wang* 1120

(Contents Continued on Page 3)

(Contents Continued from Page 2)

Almost Global and Singularity-Free Fixed-Time Sliding Mode Satellite Attitude Control: A Geometric Control Framework . . . . . *S. Barman and M. Sinha* 1135
Clutter Suppression for OTHR Based on Joint Low Rank and Group Sparse Representation . . . . . *Z. Chen, Y. Ji, Y. Zhang, Z. Dong, W. Liu, A. Chen, and J. Song* 1146
Dynamic-Command-Limiting-Based AOA Constraint Control of Hypersonic Flight Vehicle . . . . . *S. Liang, B. Xu, S. Sun, and C. Tao* 1163
Adaptive-Neural Finite-Time Sliding Mode Control for Quadrotor Helicopter Attitude Stabilization in Complex Environments . . . . . *M. Ullah, H. Gao, A. Nasir, Y. Wang, and C. Wang* 1175

CORRESPONDENCE

Asynchronous Terrestrial Signal of Opportunity-Based Self-Localization With Source Location Uncertainty: Methods and Analysis . . . . . *F. Li, T. Jin, H. Qin, and J. Qu* 1186
Single-Channel Direction Finding by Amplitude Correlation With Time-Modulated Array . . . . . *A. Cao, X. Bai, A. Gevorgyan, C. He, and R. Jin* 1197
Geometric Approach to Lateral Guidance for Reentry Vehicle . . . . . *X. Cheng, X. Song, S. Chen, and C. Li* 1208
Linear Shrinkage Coefficient-Based Source Number Estimation Using Semi-Supervised GAN With Small Samples . . . . . *C. Duan, Y. Tian, and W. Liu* 1215
AoI-Aware Uplink CR-NOMA Schemes in Satellite Internet of Things Networks . . . . . *Y. Guo, M. Lin, Y. Liu, H. Kong, J.-B. Wang, and J. Wang* 1224
A Low Probability of Intercept Method Based on Power Optimization for Frequency Diverse Array and Cooperative Jammer . . . . . *S. Zhang, H. Chen, W. Jia, and W. Wang* 1231
High-Performance Receiving Beamforming With Low-Resolution Arrays in Multisatellite Communications . . . . . *T. Shi, S. Sun, W. Sun, S. Kang, and R. Liu* 1237